

ANIMAL GENETICS & BREEDING

UNIT - I

BIO-STATISTICS AND COMPUTER APPLICATION

Theory

PROBABILITY

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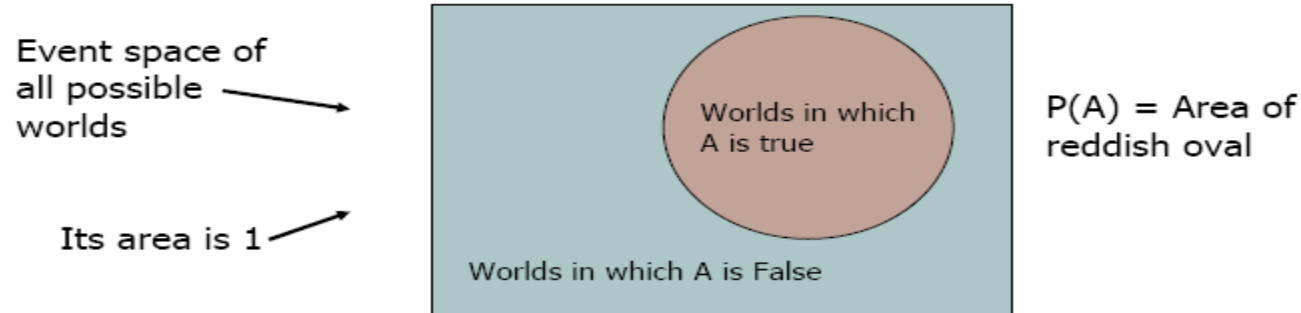
Sample space and Events

- Ω : Sample Space, result of an experiment
 - If you toss a coin twice $\Omega = \{HH, HT, TH, TT\}$
- Event: a subset of Ω
 - First toss is head = $\{HH, HT\}$
- S : event space, a set of events:
 - Closed under finite union and complements
 - Entails other binary operation: union, diff, etc.
 - Contains the empty event and Ω

Probability Measure

- Defined over (Ω, S) s.t.
 - $P(\alpha) \geq 0$ for all α in S
 - $P(\Omega) = 1$
 - If α, β are disjoint, then
 - $P(\alpha \cup \beta) = p(\alpha) + p(\beta)$
- We can deduce other axioms from the above ones
 - Ex: $P(\alpha \cup \beta)$ for non-disjoint event
$$P(\alpha \cup \beta) = p(\alpha) + p(\beta) - p(\alpha \cap \beta)$$

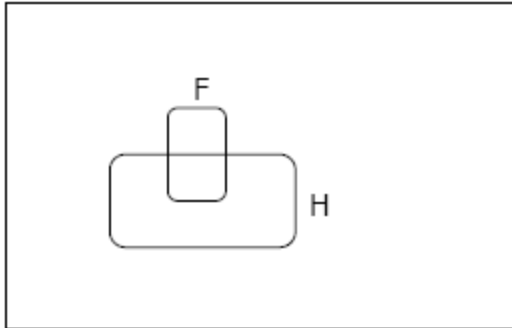
Visualization



- We can go on and define conditional probability, using the above visualization

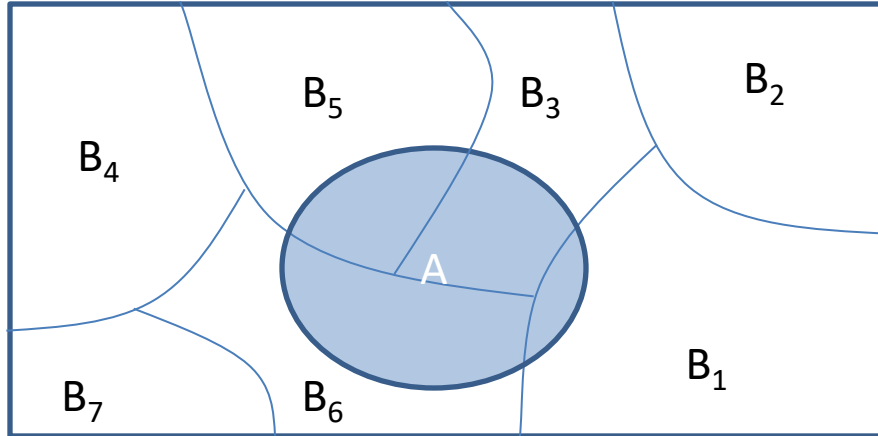
Conditional Probability

$P(F | H)$ = Fraction of worlds in which H is true that also have F true



$$p(f | h) = \frac{p(F \cap H)}{p(H)}$$

Rule of total probability

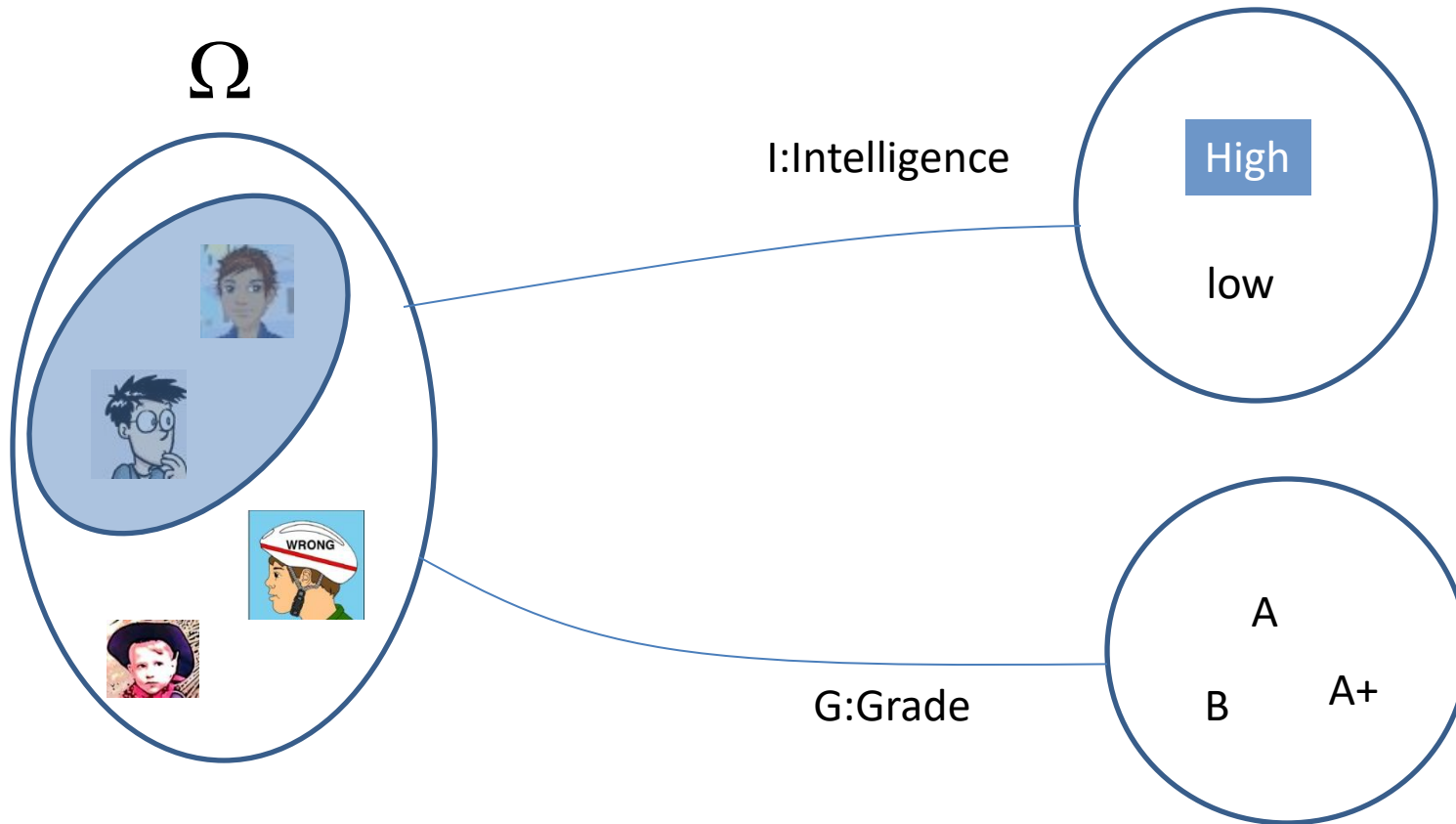


$$p(A) = \sum P(B_i)P(A|B_i)$$

From Events to Random Variable

- Almost all the semester we will be dealing with RV
- Concise way of specifying attributes of outcomes
- Modeling students (Grade and Intelligence):
 - $\Omega =$ all possible students
 - What are events
 - Grade_A = all students with grade A
 - Grade_B = all students with grade B
 - Intelligence_High = ... with high intelligence
 - Very cumbersome
 - We need “functions” that maps from Ω to an attribute space.
 - $P(G = A) = P(\{\text{student} \in \Omega : G(\text{student}) = A\})$

Random Variables



$$P(I = \text{high}) = P(\{\text{all students whose intelligence is high}\})$$

Discrete Random Variables

- Random variables (RVs) which may take on only a **countable** number of **distinct** values
 - E.g. the total number of tails X you get if you flip 100 coins
- X is a RV with arity k if it can take on exactly one value out of $\{x_1, \dots, x_k\}$
 - E.g. the possible values that X can take on are 0, 1, 2, ..., 100

Probability of Discrete RV

- Probability mass function (pmf): $P(X = x_i)$
- Easy facts about pmf
 - $\sum_i P(X = x_i) = 1$
 - $P(X = x_i \cap X = x_j) = 0$ if $i \neq j$
 - $P(X = x_i \cup X = x_j) = P(X = x_i) + P(X = x_j)$ if $i \neq j$
 - $P(X = x_1 \cup X = x_2 \cup \dots \cup X = x_k) = 1$

Common Distributions

- Uniform $X \sim U[1, \dots, N]$
 - X takes values $1, 2, \dots, N$
 - $P(X = i) = 1/N$
 - E.g. picking balls of different colors from a box
- Binomial $X \sim \text{Bin}(n, p)$
 - X takes values $0, 1, \dots, n$
 - $p(X = i) = \binom{n}{i} p^i (1-p)^{n-i}$
 - E.g. coin flips

Continuous Random Variables

- Probability density function (pdf) instead of probability mass function (pmf)
- A pdf is any function $f(x)$ that describes the probability density in terms of the input variable x .

Probability of Continuous RV

- Properties of pdf

- $f(x) \geq 0, \forall x$

- $\int_{-\infty}^{+\infty} f(x) = 1$

- Actual probability can be obtained by taking the integral of pdf

- E.g. the probability of X being between 0 and 1 is

$$P(0 \leq X \leq 1) = \int_0^1 f(x) dx$$

Cumulative Distribution Function

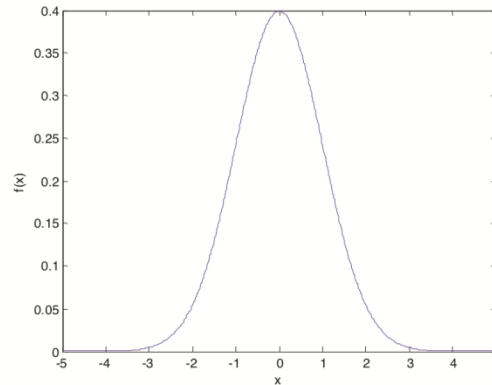
- $F_X(v) = P(X \leq v)$
- Discrete RVs
 - $F_X(v) = \sum_{v_i} P(X = v_i)$
- Continuous RVs
 - $F_X(v) = \int_{-\infty}^v f(x) dx$
 - $\frac{d}{dx} F_x(x) = f(x)$

Common Distributions

- Normal $X \sim N(\mu, \sigma^2)$

- $$f(x) = \frac{1}{\sigma\sqrt{2\pi}} \exp\left(-\frac{(x - \mu)^2}{2\sigma^2}\right)$$

- E.g. the height of the entire population



Joint Probability Distribution

- Random variables encodes attributes
- Not all possible combination of attributes are equally likely
 - Joint probability distributions quantify this
- $P(X = x, Y = y) = P(x, y)$
 - Generalizes to N-RVs
 - $\sum_x \sum_y P(X = x, Y = y) = 1$
 - $\int \int_{x y} f_{X,Y}(x, y) dx dy = 1$

Chain Rule

- Always true
 - $P(x, y, z) = p(x) p(y|x) p(z|x, y)$
 $= p(z) p(y|z) p(x|y, z)$
 $= \dots$

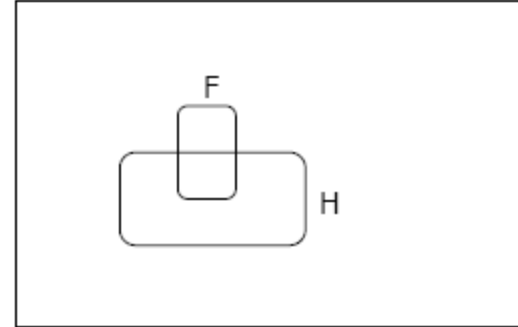
Conditional Probability

$$P(X = x | Y = y) = \frac{P(X = x \cap Y = y)}{P(Y = y)}$$

events

But we will always write it this way:

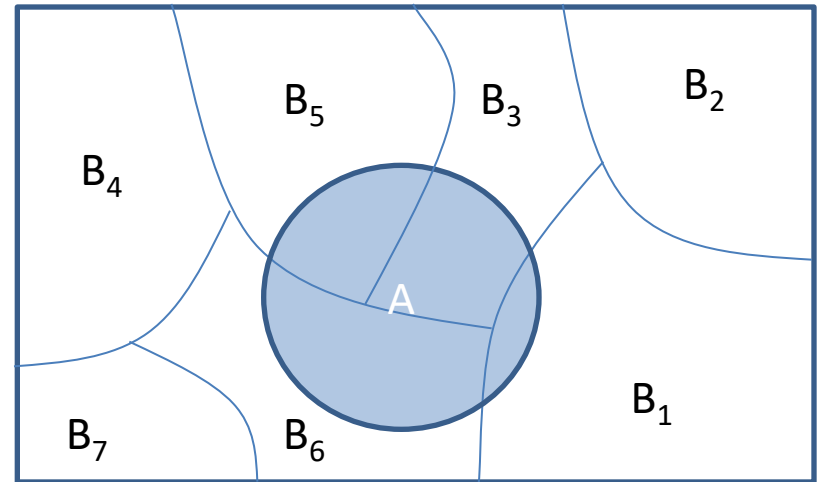
$$P(x | y) = \frac{p(x, y)}{p(y)}$$



Marginalization

- We know $p(X, Y)$, what is $P(X=x)$?
- We can use the law of total probability, why?

$$\begin{aligned} p(x) &= \sum_y P(x, y) \\ &= \sum_y P(y)P(x|y) \end{aligned}$$



Marginalization Cont.

- Another example

$$\begin{aligned} p(x) &= \sum_{y,z} P(x, y, z) \\ &= \sum_{z,y} P(y, z) P(x | y, z) \end{aligned}$$

Bayes Rule

- We know that $P(\text{rain}) = 0.5$
 - If we also know that the grass is wet, then how this affects our belief about whether it rains or not?

$$P(\text{rain} \mid \text{wet}) = \frac{P(\text{rain})P(\text{wet} \mid \text{rain})}{P(\text{wet})}$$

$$P(x \mid y) = \frac{P(x)P(y \mid x)}{P(y)}$$

Bayes Rule cont.

- You can condition on more variables

$$P(x | y, z) = \frac{P(x | z)P(y | x, z)}{P(y | z)}$$

Independence

- X is independent of Y means that knowing Y does not change our belief about X .
 - $P(X|Y=y) = P(X)$
 - $P(X=x, Y=y) = P(X=x) P(Y=y)$
 - The above should hold for all x, y
 - It is symmetric and written as $X \perp Y$

Independence

- X_1, \dots, X_n are independent if and only if

$$P(X_1 \in A_1, \dots, X_n \in A_n) = \prod_{i=1}^n P(X_i \in A_i)$$

- If X_1, \dots, X_n are independent and identically distributed we say they are *iid* (or that they are a random sample) and we write

$$X_1, \dots, X_n \sim P$$

CI: Conditional Independence

- RV are rarely independent but we can still leverage local structural properties like Conditional Independence.
- $X \perp Y \mid Z$ if once Z is observed, knowing the value of Y does not change our belief about X
 - $P(\text{rain} \perp \text{sprinkler's on} \mid \text{cloudy})$
 - $P(\text{rain} \not\perp \text{sprinkler's on} \mid \text{wet grass})$

Conditional Independence

- $P(X=x \mid Z=z, Y=y) = P(X=x \mid Z=z)$
- $P(Y=y \mid Z=z, X=x) = P(Y=y \mid Z=z)$
- $P(X=x, Y=y \mid Z=z) = P(X=x \mid Z=z) P(Y=y \mid Z=z)$

We call these factors : very useful concept !!



The Big Picture

